



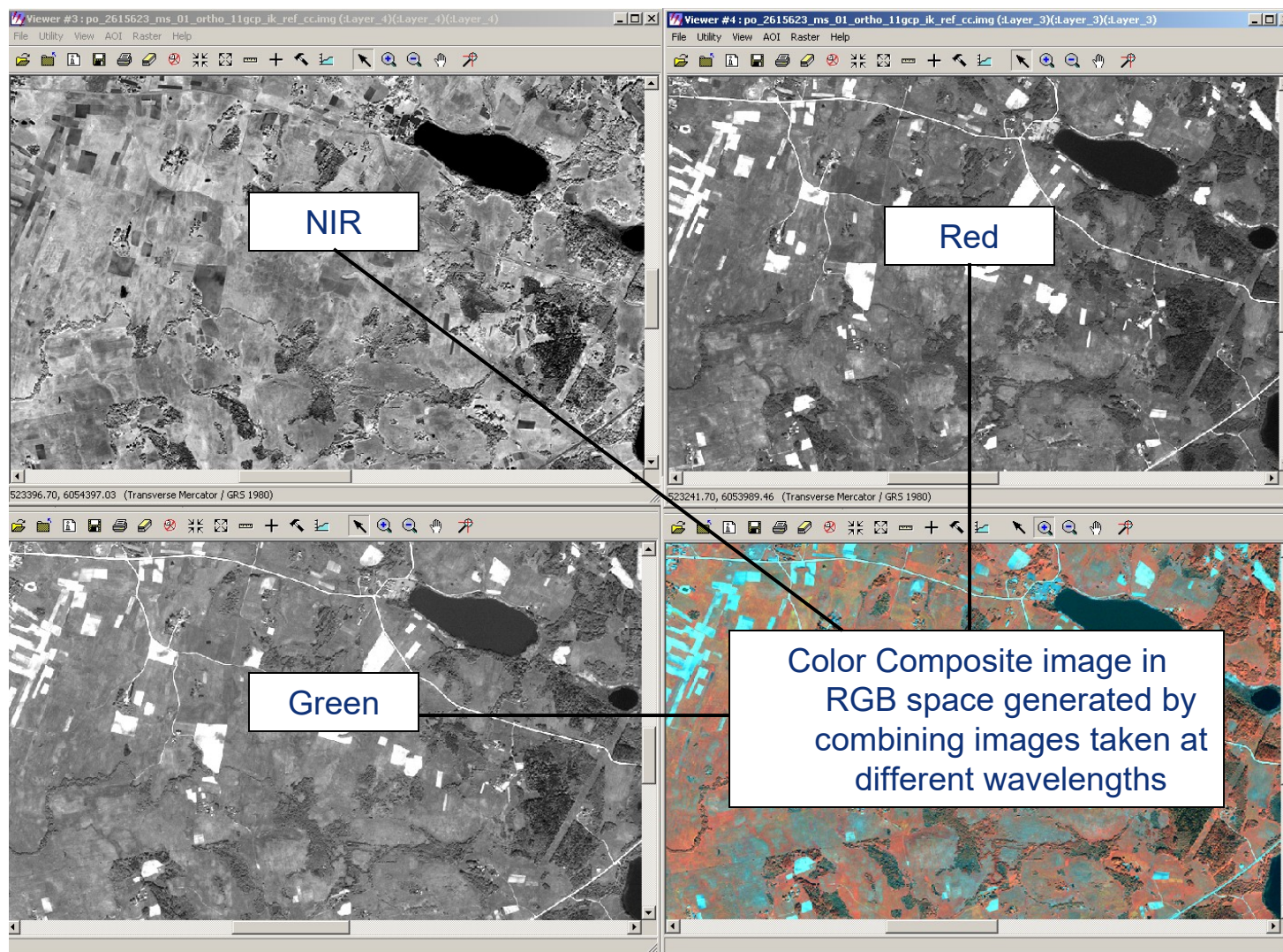
Use of Pan image only for the CwRS

Rationale

- VHR prime sensors used in CwRS (IK and QB) close to acquisition limits
 - New VHR (PAN+MS) sensors with GSD < 1m still under evaluation (Kompsat -1, GeoEye - 1)
- New VHR (PAN only) sensors with GSD < 1m (EROS B, WV-1)
- Could these new VHR PAN be used for CwRS as VHR prime sensors?
 - Limitation due to lack of multispectral (MS) component for the VHR
 - Possible combination with appropriate HR image

But what is the impact on the parcel measurements? Is it significant enough?

What is PAN? What is MS?

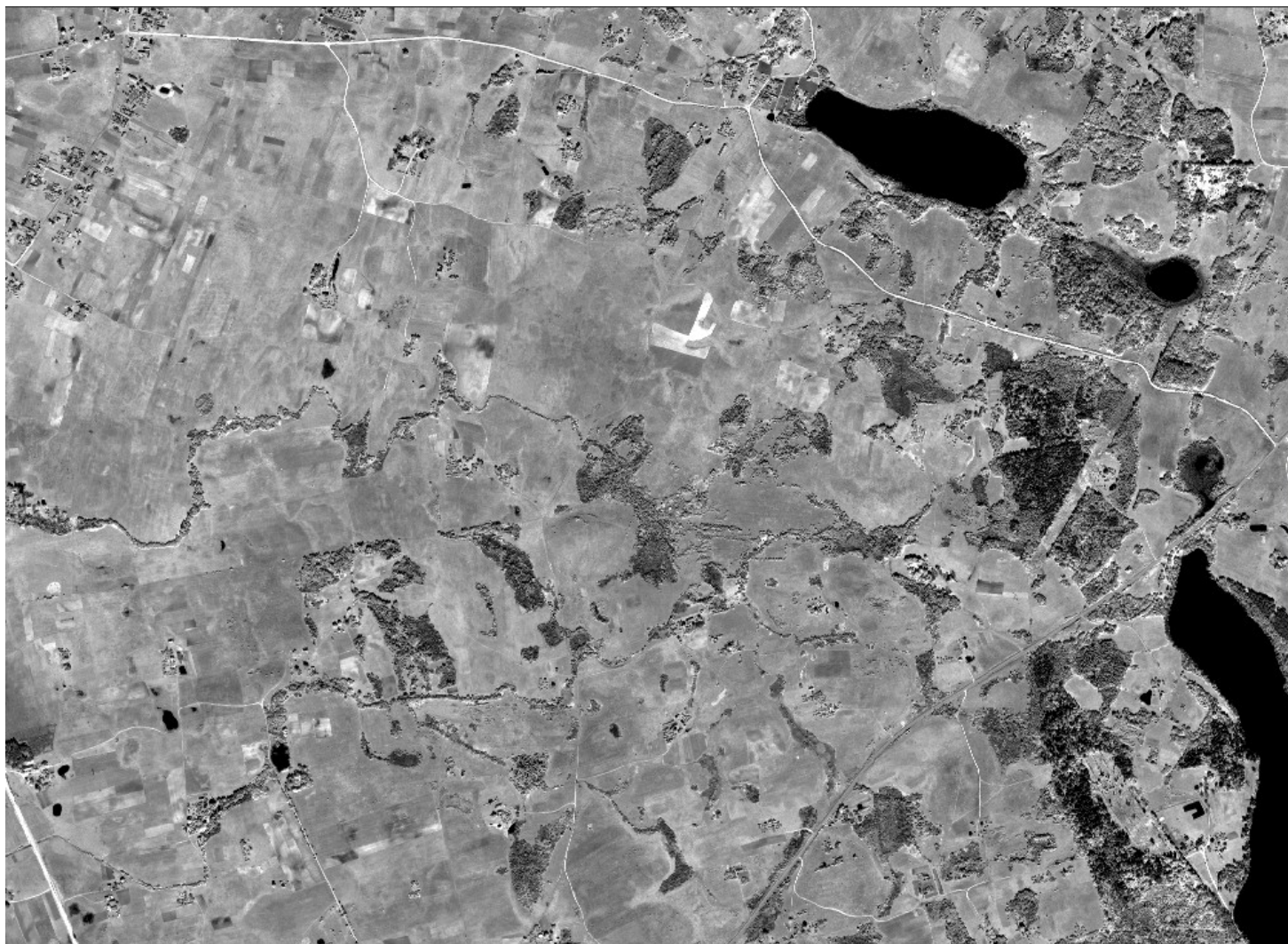


The panchromatic of Toni Frissell



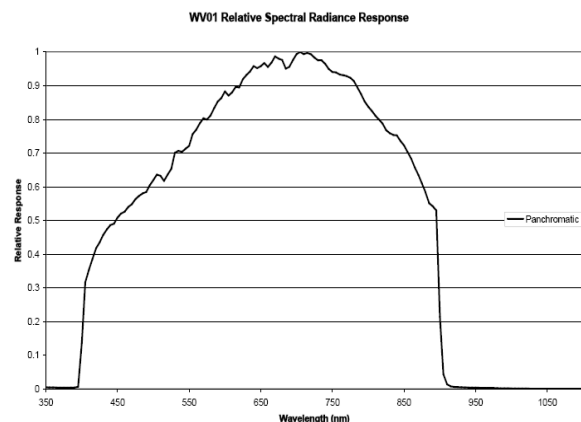
A panchromatic image is acquired with a sensor that is sensitive to all or most of the visible spectrum.

The panchromatic of IKONOS and Quickbird



VHR Panchromatic vs. Panchromatic

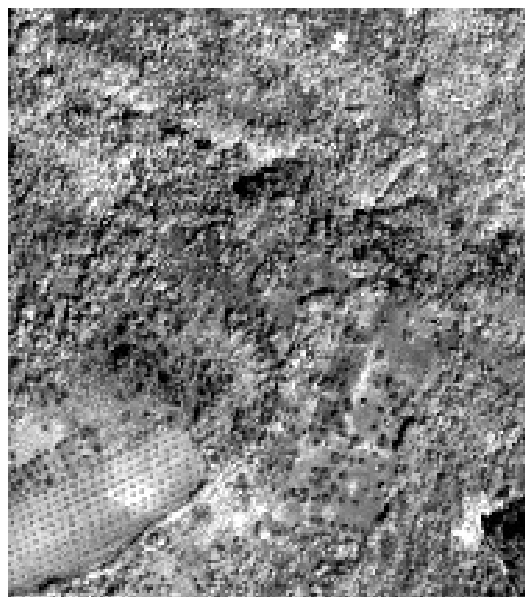
PAN range of VHR satellites



WW1 Relative spectral Radiance Response

Different spectral range

VHR PAN, GSD 0.6m

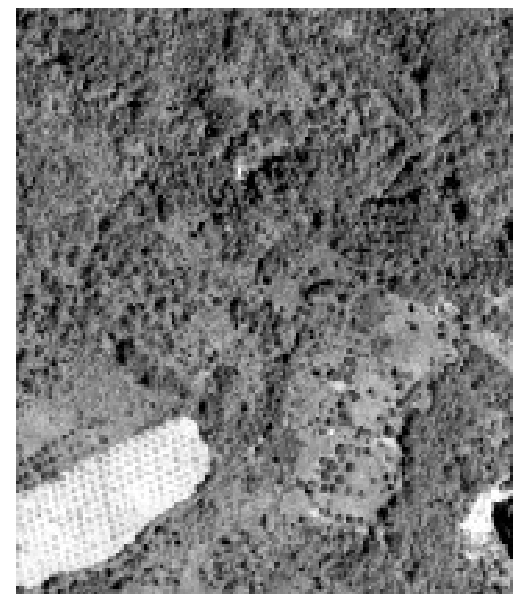


400 nm

900 nm

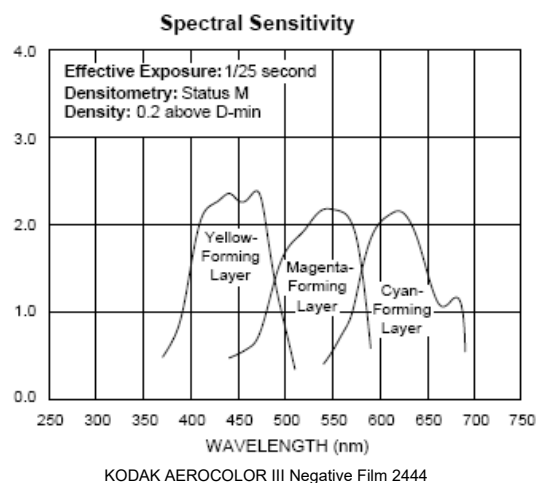


Aerial B&W, GSD 1.0m

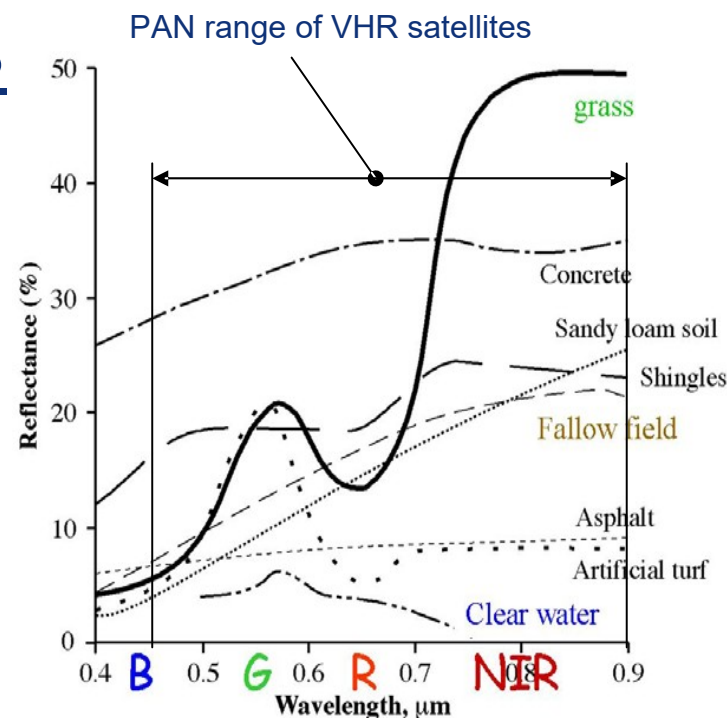
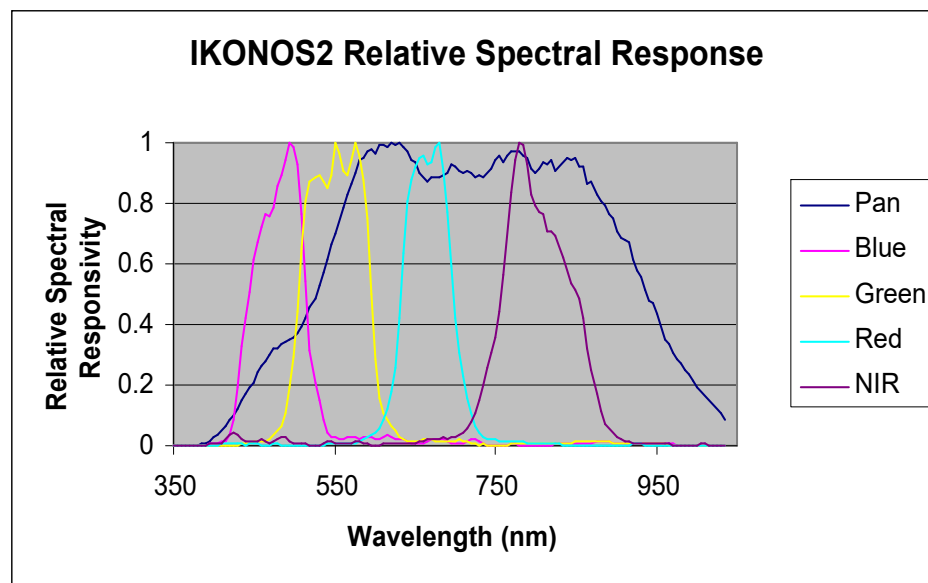


400 nm

700 nm



PAN and MS - Definitions



- The multispectral image represents the reflectance data in several discrete spectral bands.
- The panchromatic image contains only one wide band of reflectance data.

Panchromatic images are collected with higher spatial resolution than the multispectral image, due to the broad spectral range (more light energy)

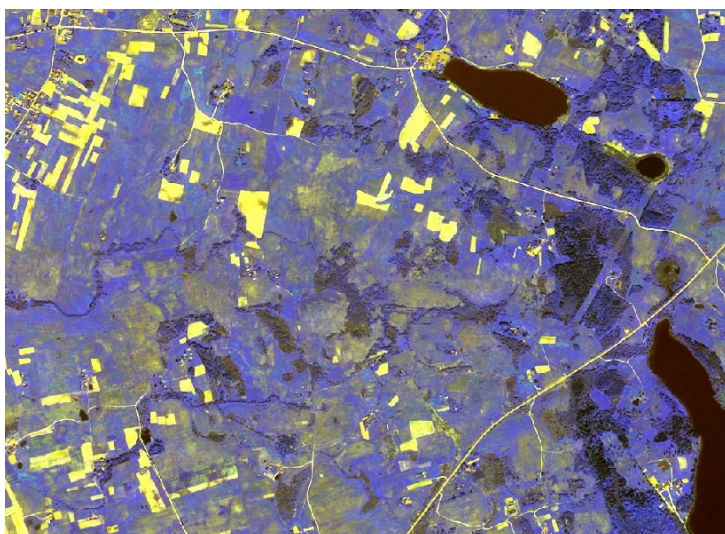
The Color Composite – A Trick for the Eye



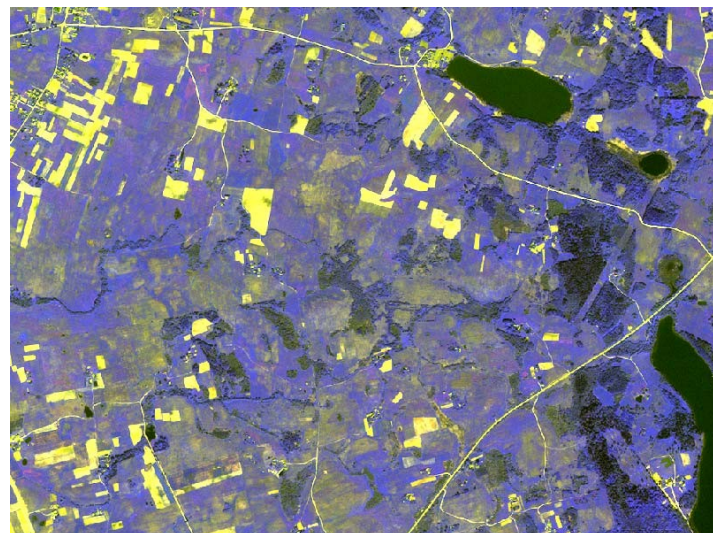
R NIR
G Red
B Blue



R Red
G NIR
B Blue



R Blue
G Red
B NIR



R Red
G Blue
B NIR

Spatial and Spectral Resolution



QB PAN 0.6 m GSD



QB XS 2.4 m GSD

Image Resolution and Information Content

VHR PAN

Good spatial resolution

High detail, more objects are resolved

Texture more visible

Smoothness of objects preserved

Poor spectral resolution

Spectral variations are difficult to detect

Low sensitivity to change of reflection

Compactness of objects is less evident

VHR MS

Poor spatial resolution

Low detail, less objects are resolved

Texture less visible

Smoothness of objects decreased

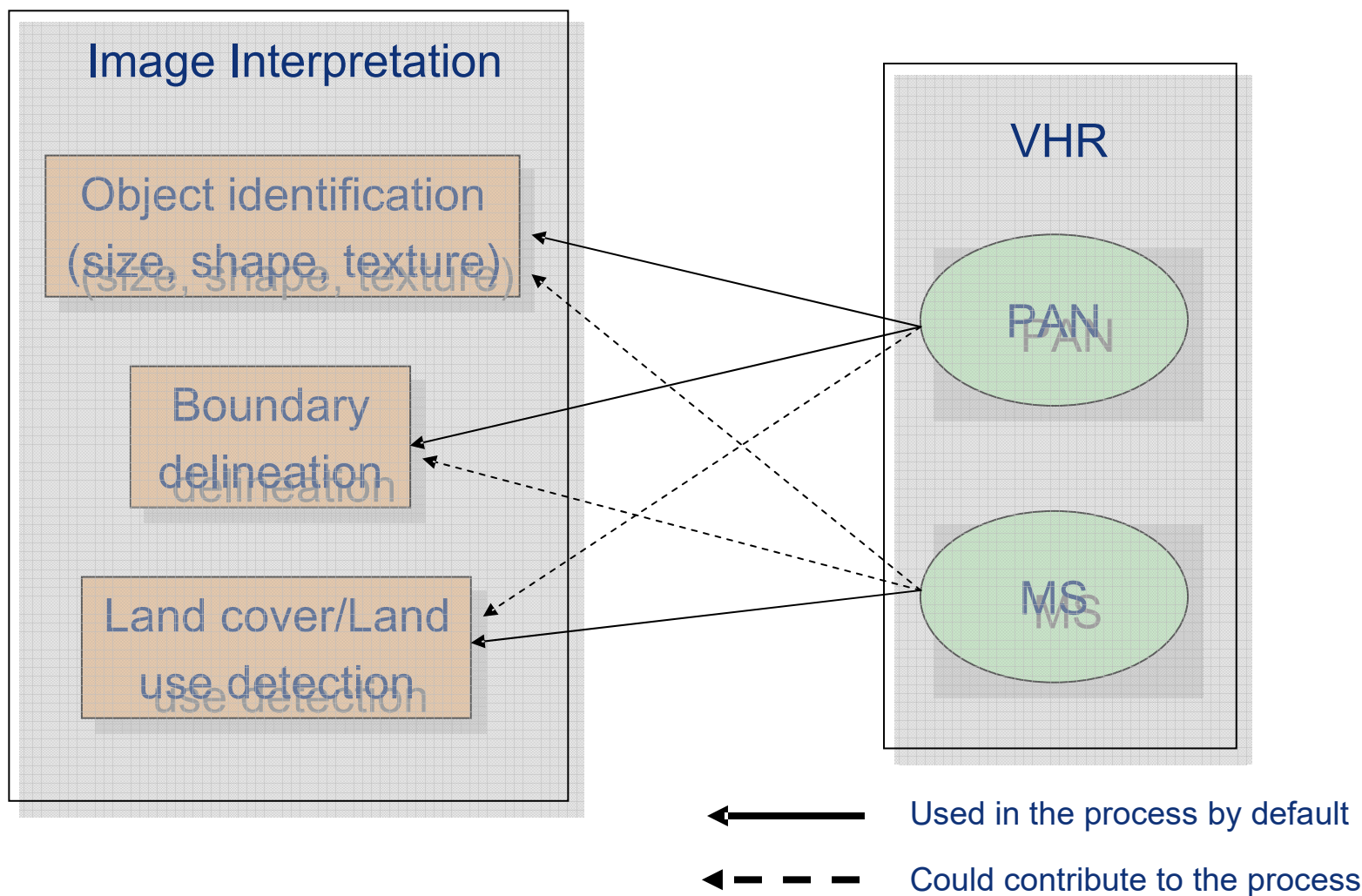
Good spectral resolution

Spectral variations are easy to detect

High sensitivity to change of reflection

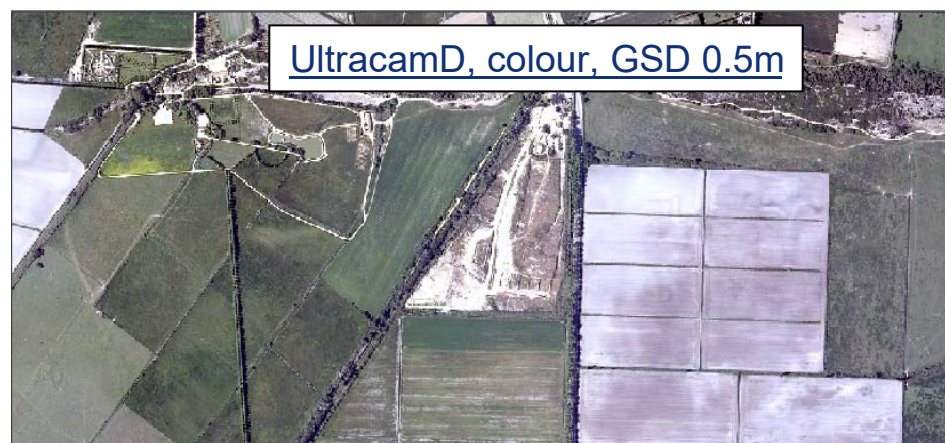
Compactness of objects is better presented

PAN + MS in the context of CwRS



Examples – WV-1 over Mausanne (FR)

Note: Images acquired in different years and seasons!



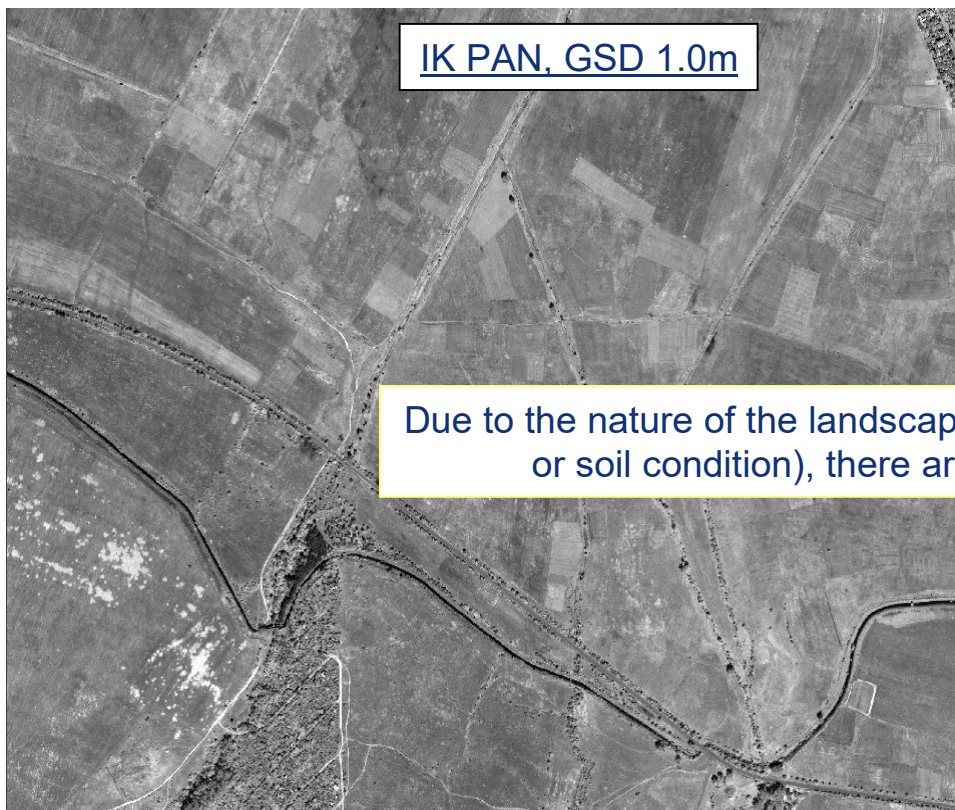
Due to the nature of the landscape (hedges, trees rows), there is no significant difference in object recognition



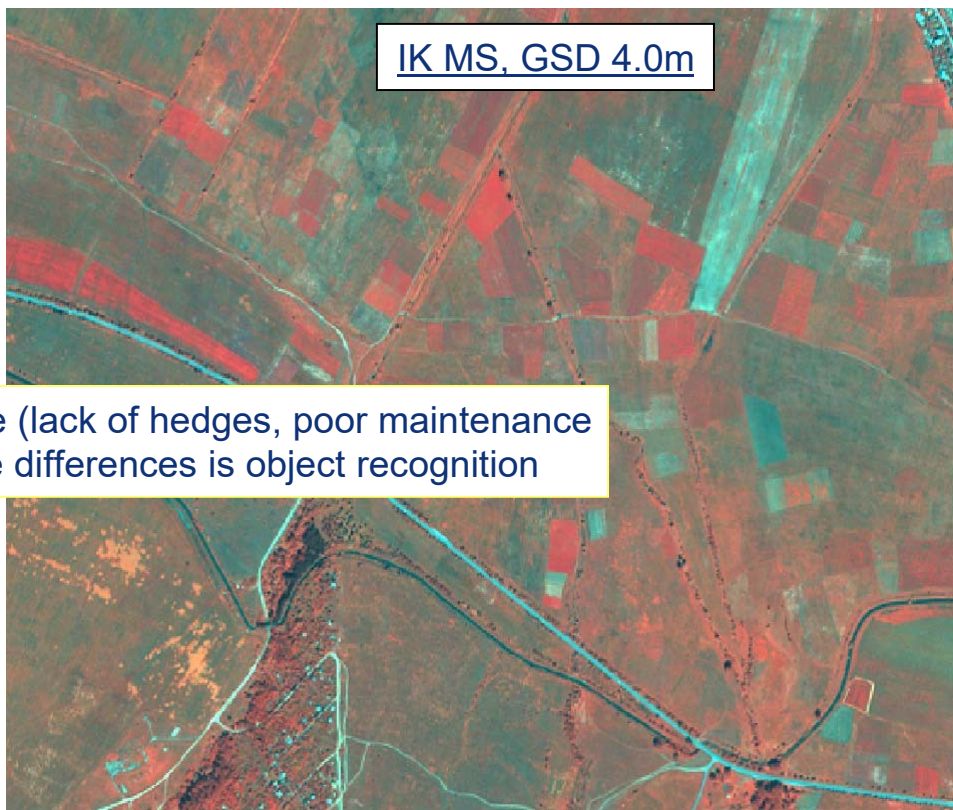
Examples – IK over Sofia (BG)

Images acquired simultaneously (bundle product)

IK PAN, GSD 1.0m



IK MS, GSD 4.0m



Due to the nature of the landscape (lack of hedges, poor maintenance or soil condition), there are differences in object recognition

The Case Study

Test Area:

QC site from CwRS 2007: STAK (LT)

Primary sensor: IKONOS (PAN+MS)

Backup sensor: EROS B (PAN only)

Backup is acquired a day after the dedicated.

QC vector data available

Measured parcels from Contractor and LPIS data

Why this site?

- Prime and Backup were acquired almost simultaneously (one day difference). Same phenological conditions for the vegetation
- Parcels structure without hedges or rows of trees, where the role of MS might be decisive.

The Case Study (2)

$\frac{3}{4}$ Objective of the study

- to identify a set of agricultural parcels on both IKONOS and EROS B
- to assess the measurement tolerance thought the reproducibility limit (see Session T3, ID 18)

$\frac{3}{4}$ How to do that?

- With 4 Operators
- Working independently on both image datasets (first EROSB, then IKONOS)
- Delineating 3 times (through CAPI) the same set of parcels in random sequence
- Analyzing the results and computing the statistics (see see Session T3, ID 18)

$\frac{3}{4}$ Preparatory work

- Initial image data analysis and pre-processing
- Parcel Sample Selection, from the CwRS vector dataset
- Definition of methodology and interpretation rules (see Session T3, ID 18)

Initial image data analysis and pre-processing

Poor quality of the pansharpened
“reference” image of IKONOS

Due to slight improper registration of the
PAN and MS components of the Bundle
product

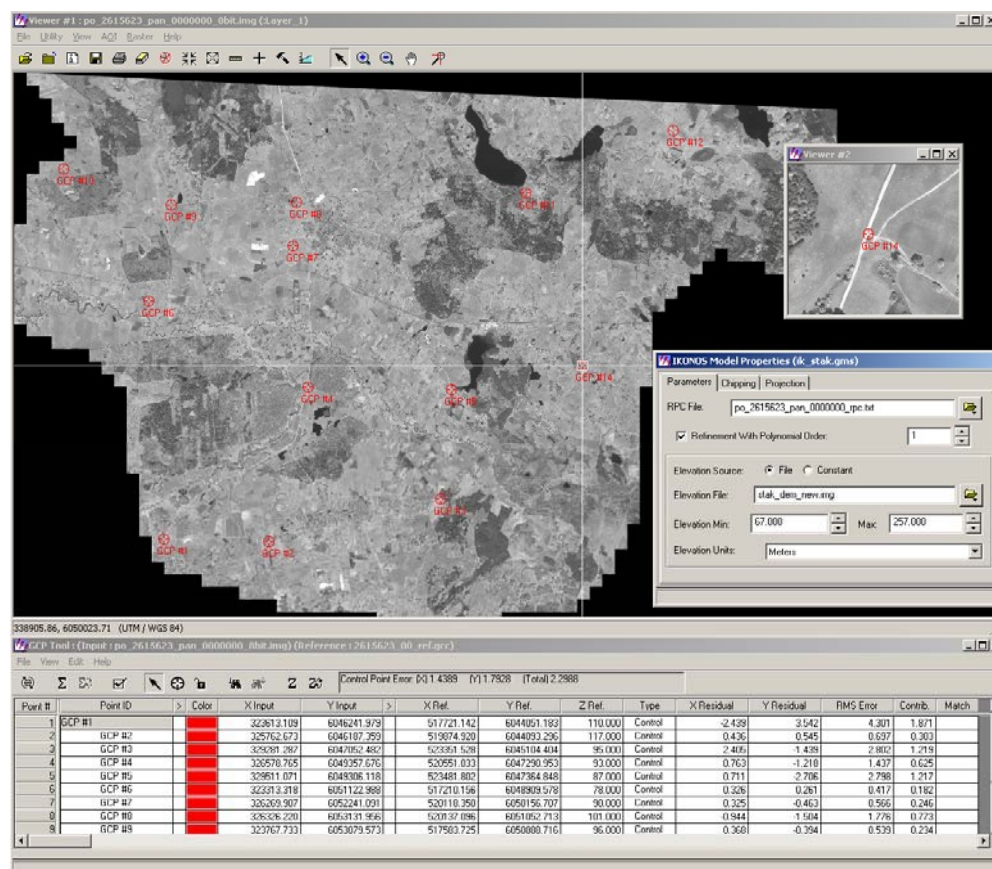


New pansharpened image produced

After new orthorectification of both PAN
and MS



Pre-processing – Orthorectification of the IKONOS



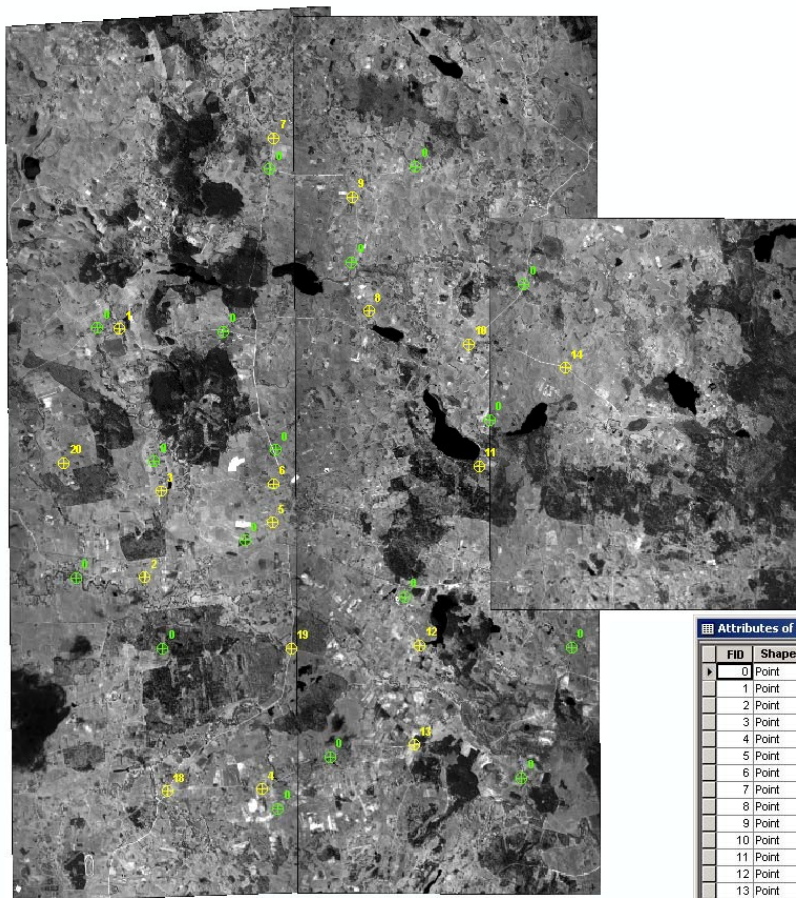
With the same ground control points and DEM used for the correction of EROS B

With the same Geometric model (RPC file and poly order) for both PAN and MS

Image fusion using:

Principal Component Method
Cubic Convolution

Pre-processing – Accuracy checks of EROSB



With the ground control points
and the PRESS method

RMSE_{1d} between 1.5 and 3
meters for the different
scenes

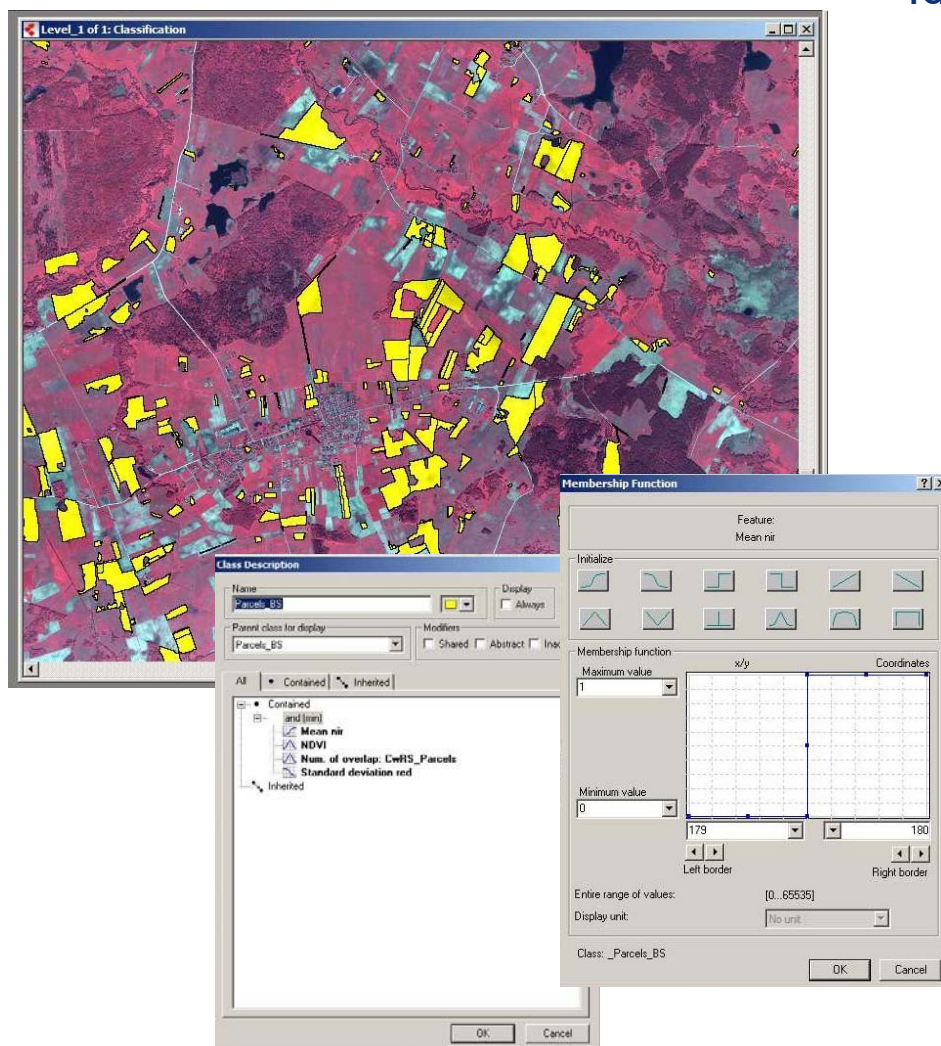
Some scenes and areas
excluded from the test

Attributes of checkpoints_EROSB_pan_ortho_vslPIS_STAK

FID	Shape	ID	X	Y	Xref	Yref
0	Point	0	521435.711342	6044830.28586	521437.988765	6044830.64546
1	Point	0	526930.720352	6047321.83924	526933.960945	6047320.75904
2	Point	0	523131.691673	6048468.1295	523133.642201	6048469.75494
3	Point	0	525795.906195	6044355.52407	525798.590715	6044354.92751
4	Point	0	519490.450523	6049743.40672	519487.655383	6049744.26676
5	Point	0	515642.02333	6048901.36146	515641.015145	6048902.08159
6	Point	0	520185.301096	6051826.48397	520183.646194	6051826.10148
7	Point	0	520247.999971	6043662.94293	520247.687228	6043661.06647
8	Point	0	517419.357258	6051564.86228	517417.300875	6051566.2332
9	Point	0	525062.190452	6052504.97088	525057.228383	6052502.94638
10	Point	0	517620.39636	6047297.64716	517620.128749	6047294.98708
11	Point	0	519007.722094	6054522.82935	519002.349124	6054521.38762
12	Point	0	520053.283419	6058210.27637	520049.413226	6058210.80412
13	Point	0	525846.187499	6055590.13831	525845.567913	6055591.76407
14	Point	0	523379.16342	6058276.26395	523377.72616	6058275.96137
15	Point	0	521916.144929	6056092.3723	521912.968053	6056094.75496

Record: 1 Show: All Selected Records (0 out of 17)

Parcel Sample Selection



Identification of potential candidates on the base of selected spectral characteristics

- Parcels with DN values in certain range of the mean red and NDVI

Spatial intersection with the vectors from the CwRS

- Initial selection of 230 parcels from the CwRS dataset

Stratification of the selected CwRS parcels based on their size

- Random selection in each strata (150 parcels)
- Final set for the current test: 56 parcels

Definition of methodology and interpretation rules



Operators delineate the parcel on the base of the image only (IK or EROSB), following the shape of the measured parcels from the CwRS (displayed on separate screen)



The crop boundaries of the parcel were delineated, excluding any other type of land cover.

In case of multiple crops, the vector contour from the CwRS should be considered.



First Results

Feedback from Operators

- In general no problem for identification of the parcels on EROS B
- In few cases even easier than the IKONOS
- Many of the problematic cases on EROS B were found difficult also on IKONOS

Statistics

- Reproducibility limit for EROS B – **1.34** meters
- Reproducibility limit for IKONOS – **1.35** meters

Reproducibility limits calculated base on mean buffer using mean area and mean perimeter

First Conclusions

EROS B shows similar capability for parcel measurements like IKONOS

- Smaller tolerance expected for EROSB, considering its GSD of 0.7 m

The higher spatial resolution of EROS B is able to compensate the lower spectral resolution.

Pan-sharpening might have adverse effects on the spatial resolution (fuzzy boundaries, blurring, poor resampling, etc.)

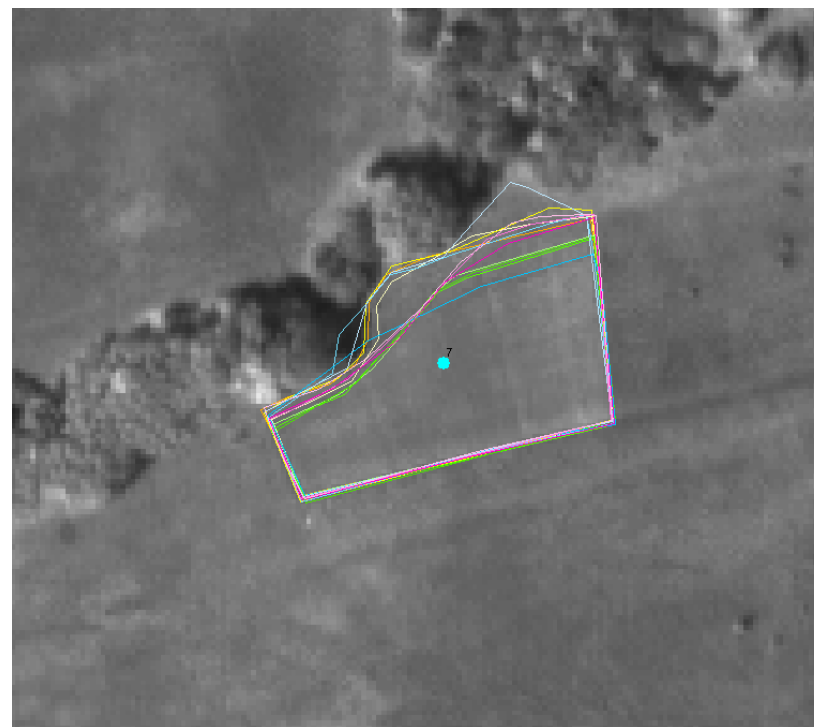
Follow-up:

1. Larger sample
2. Comprehensive statistics (including Normality tests, outlier detection, etc.)
3. Another test area

Some examples



Some examples (2)

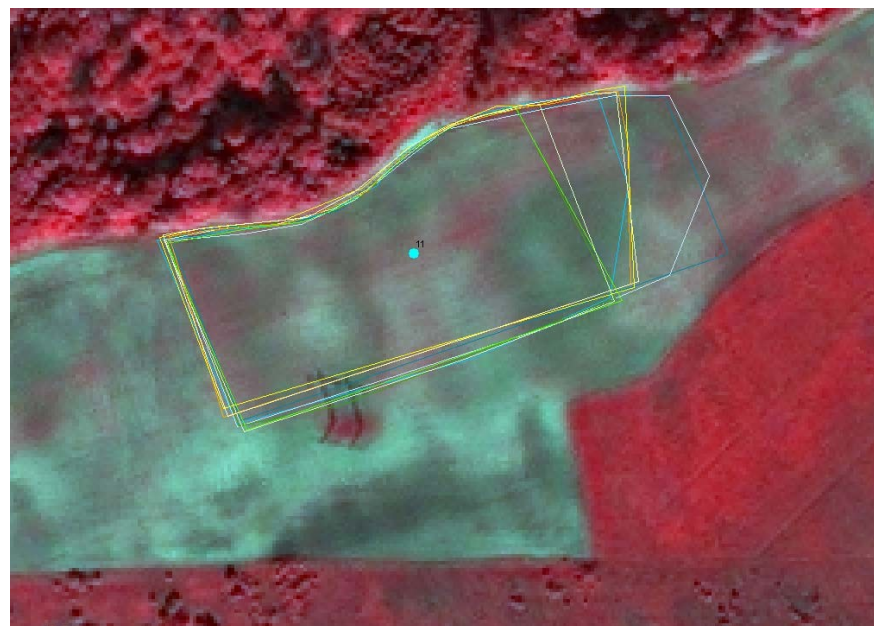


Some examples – Same parcel on both images

EROS B



IKONOS





Maurizio Polese

Thank you for your attention